GS / NOI

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Class:10+2 Unit: III Topic: Magnetic Field due to current

<u>SYLLABUS</u>: UNIT-III-A,B

Concept of magnetic field, Oersted's experiment, Biot-Savart law, magnetic field due to an infinitely long current carrying straight wire and a circular loop; Ampere's circuit law and its applications to straight and toroidal solenoids; Force on a moving charge in uniform magnetic and electric fields, Cyclotron; Force on current – carrying conductor in a uniform magnetic field. Forces between two parallel current- carrying conductors-definition of ampere; Torque experienced by a current loop in a uniform magnetic field, moving coil galvanometer- its current sensitivity and conversion to ammeter and voltmeter.

Current loop as a magnetic dipole and its magnetic dipole moment; Magnetic dipole moment of a revolving electron; Magnetic field intensity due to magnetic dipole (bar magnet) along the axis and perpendicular to the axis; Torque on a magnetic dipole (bar magnet) in a uniform magnetic field; Bar magnet as an equivalent solenoid, Magnetic field lines' Earth's magnetic field and magnetic elements; Para-dia and ferro-magnetic substances with examples, Electromagnets and permanent magnets.



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## Q.1. Define magnetic field strength B? Units? Dimensions?

Ans.  $B \rightarrow$  Magnetic flux per unit Area

$$B = \frac{\Phi_m}{A} \qquad \text{Where } \Phi_m \Rightarrow \text{magnetic flux} \\ A \Rightarrow \text{Area} \\ \text{S.I. Unit:} \qquad B = \frac{Magnetic Flux}{Area} \\ = \frac{weber}{m^2} (wb/m^2) \\ \hline 1 \text{ tesla} = \frac{1 \text{ } wz}{m^2} \\ \hline 1 \text{ tesla} = \frac{1 \text{ } wz}{m^2} \\ \hline Dimensions: \quad \vec{f} = q(\vec{V} \times \vec{B}) \\ f = q V B \\ \hline Dimensions \text{ of, } B = \frac{MLT^{-2}}{AT(LT^{-1})} \qquad B = \frac{f}{q.V} \\ \hline (\vec{B}) = [M^1 L^{0} T^{-2} A^{-1}] \\ \vec{f} = q(\vec{V} \times \vec{B}) \\ f = q V B \text{ sin } 90 \\ \frac{f}{q V \sin 90} = B \\ \end{bmatrix}$$

Magnetic field strength can be defined as Force acting on unit charge moving with unit velocity perpendicular to magnetic field.

Ans.

 $\vec{f} = q(\vec{V} \times \vec{B})$ 

Case-I.

 $\vec{f} = q(\vec{V} \times \vec{B})$  $\vec{f} = qVB \sin 0$  $\vec{f} = 0$ 

 $\vec{V} \mid \mid \vec{B}, \theta = 0$ 



Whenever charge moves parallel to magnetic field, force acting on charge is *ZERO* 

<u>Case-II</u> . $\Theta =$
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$$f = q(\vec{V} \times \vec{B})$$

*f* = q V B Sin 180

Whenever charge moves antiparallel to magnetic field, force acting on charge is *ZERO* 

Case-III.

 $f = q(\vec{V} \times \vec{B})$ 

 $\Theta = 90^{\circ}$ 

f = q V B Sin 90

*f* = q V B

 $f_{max}$  = q.V.B



S

N  $\xrightarrow{\vec{B}}$   $\xrightarrow{\vec{B}}$ 



Force is max whenever charge moves  $\perp$  to magnetic field

Direction:-

 $\vec{f}$  is normal to  $\vec{V}$  and  $\vec{B}$ 

 $\vec{f}$  is inwards as per right hand screw rule

Q.3. Explain Biot – Savarts Law?



Direction of  $I \ \vec{dl} \ge \vec{r}$  is inwards as per right hand screw rule

# Q.4. Use Biot Savarts Law to find field at the centre of ring of radius *r* carrying current *l*.

Ans. Step 1.

Apply Biots Savarts Law for small elements JK

$$d\vec{B} = \frac{\mu_0}{4\pi} \cdot \frac{I \, d\vec{l} \, x \, \vec{r}}{r^3}$$
$$dB = \frac{\mu_0}{4\pi} \cdot \frac{I \, dl \, r \, \sin 90^0}{r^3}$$
$$= \frac{\mu_0}{4\pi} \cdot \frac{I \, dl(1)}{r^2}$$
$$dB = \frac{\mu_0}{4\pi} \cdot \frac{I \, dl}{r^2}$$

## <u>Step 2.</u>

Total field at 0 i.e. at centre of ring

## Integrate both sides

$$\int dB = \int \frac{\mu_0}{4\pi} \frac{I \, dI}{r^2}$$
$$= \frac{\mu_0 \cdot I}{4\pi r^2} \cdot \int dl$$
$$= \frac{\mu_0 \cdot I \, 2\pi r}{4\pi r^2}$$
$$B = \frac{\mu_0 \cdot I}{2 \cdot r}$$
$$For arc of angle \theta$$
$$B = \frac{\mu_0 \cdot I}{4\pi r} \cdot \left(\frac{\theta}{2\pi}\right)$$
$$For full circle \theta = 2\pi$$
$$B_{circle} = \frac{\mu_0 \cdot I}{4\pi r} \cdot (2\pi)$$

$$B_{circle} = \frac{\mu_0.I}{2.r}$$





#### Q.5. Use Biot Savarts Law to find field due to current carrying conductor of finite length?

Ans.

 $\frac{\mu_0}{4\pi} \cdot \frac{\mathrm{I}\,\overrightarrow{\mathrm{dl}}\,\mathrm{x}\,\vec{r}}{r^3}$  $\mathsf{d}\vec{B}$ =

Step 1.

Field due to I  $\overrightarrow{dl}$ 

$d\vec{B}$	=	$\frac{\mu_0}{4\pi} \cdot \frac{\mathbf{I}\vec{\mathbf{dl}}\mathbf{x}\vec{r}}{r^3}$
	=	$\frac{\mu_0}{4\pi} \cdot \frac{\text{I.dl r.} \sin(\theta)}{r^3}$
	=	$\frac{\mu_0}{4\pi}$ . $\frac{\text{I.dl.r.sin}\theta}{r^3}$

## Step 2.

Integrating both sides

dB	=	$\int \frac{\mu_0}{4\pi} \frac{I  \mathrm{dl}  \mathrm{r} \sin \theta}{r^3}$
В	=	$\frac{\mu_{0.I}}{4\pi}\int \frac{\mathrm{Idlrsin\theta}}{r^3}$
В	=	$\frac{\mu_{0.I}}{4\pi} \int \frac{\mathrm{dl}\cos\phi}{r^2} \qquad \begin{array}{l} \Phi + \Phi = 90^{\circ} \\ \mathrm{Sin}\theta = \cos\Phi \end{array}$
	=	$\frac{\mu_{0.I}}{4\pi}\int \frac{\operatorname{asec}^2\varphi.\ \mathrm{d}\varphi.\ \cos\varphi}{a^2 \operatorname{sec}^2\varphi}$
	=	$\frac{\mu_{0.I}}{4\pi}\int cos\varphi \ d\varphi$
	=	$\frac{\mu_{0,I}}{4\pi} \left  \sin \phi \right  \begin{pmatrix} \phi = \phi_1 \\ \phi = \phi_2 \end{pmatrix}$
В	=	$\frac{\mu_{0,I}}{4\pi a}$ (sin $\Phi_1$ + sin $\Phi_2$ )



## **Mathematical**

$\frac{l}{a}$	=	Tan φ
I	=	a Tan φ
dl	=	a <i>sec</i> ²q.dq
Also <u>a</u> r	=	cos φ
r	=	a sec ф

Special Cases:

<u>Case-I</u>: infinite conductor (at centre)

$$\Phi_{1} = \Phi_{2} = 90^{0}$$

$$B = \frac{\mu_{0.I}}{4\pi a} (\sin 90^{0} + \sin 90^{0})$$

$$B = \frac{\mu_{0.I}}{4\pi a}$$



Case-II: Infinite conductor (at end)





#### Case-III:

Length of the conductor is finite say L and point P lies on right bisector of conductor, then  $\Phi_1 = \varphi_2 = \varphi$ 

$$\operatorname{Sin} \phi = \frac{L/2}{\sqrt{a^2 + \left(\frac{L}{2}\right)^2}} = \frac{L}{\sqrt{4a^2 + L^2}}$$
$$B = \frac{\mu_{0.I}}{4\pi a} (\sin \phi + \sin \phi)$$



#### Q.6. Compare Electric and Magnetic Circuit?

#### Ans. Electric Circuit

- 1. What causes current in the Electric Circuit?
- Ans. *Emf* (Electro motive force)



#### **Magnetic Circuit**

- 1. What causes magnetic flux in magnetic circuit?
- Ans. *Mmf* (Magneto motive force)



- 2. Current, I
- 3. Resistance,  $R = \frac{l}{\sigma . A}$   $\bigvee$ Conductivity of material
- 2. Magnetic flux, φ
- Reluctance, R<sub>e</sub> {opposition to flow of magnetic flux}

$$R_e = \frac{l}{\mu.A}$$
Permeability

Iron has high permeability wood has low permeability

$$\mu = \mu_0. \ \mu_r$$
  
 $\mu = \mu_0. \ \mu_r$   
 $\mu = \mu_0. \ \mu_r$ 

 $\mu_0 \rightarrow$  permeability of free space and  $\mu_0 = 4\pi \times 10^{-7}$  in SI units.

4. H, Magnetising field intensity =

$$H = \frac{m.m.f}{l} = \frac{NI}{l}$$

 $N \rightarrow$  number of turns  $l \rightarrow$  length of magnetic circuit

4. *E*, Electric field intensity =

 $E = \frac{V}{l} = \frac{e.m.f}{length}$ 

### **Electric Circuit**

5. J 
$$=\frac{I}{A}$$

Current density

#### 6. Ohm's Law

$$V = IR$$
$$I = \frac{V}{R}$$

$$=\frac{e.m.f}{R}$$

## **Magnetic Circuit**

5. Magnetic flux density

$$= \frac{manetic flux}{Area}$$
$$= \frac{\Phi}{A}$$

φ

 $\vec{B}$ 

$$= \frac{m.m.f}{R_e}$$

$$\Phi = \frac{N.I}{R_e}$$

$$\Phi = \frac{N.I}{R_e}$$

$$=\frac{N.I}{\left(\frac{l}{\mu A}\right)}$$

$$\frac{\Phi}{A} = \frac{N.I\mu}{l}$$

$$\mathsf{B} = \frac{\mu(N.I)}{l}$$

 $[H = \frac{N.I}{l} \text{ is } m.m.f. \text{ per unit length}]$ 

 $B = \mu H$ 

Magnetic flux density depends upon material but *H* does not depend on material.

Ans. m.m.f in part PQ is = H.dl

" Total *m*. *m*. *f* in closed loop"

=∮ H.dI



"Total *m*. *m*. *f* in a closed loop is equal to total current contained".



- Q.8. Use Ampere-Circuit Law to find magnetic field due to current carrying infinite conductor.
- Ans. <u>Step 1</u>.

Apply ampere circuit law in loop, Total *m.m.f.* in closed loop = Total current contained

<u>Step 2</u>.

Take H  $\rightarrow$  constant

H.∮dl = I

H.2
$$\pi r$$
 = I (As  $\oint dl = 2\pi r$ )

$$H = \frac{I}{2\pi r}$$
$$B = \mu_0 H$$

B = 
$$\frac{\mu_0 I}{2\pi r}$$







Q.9. Find magnetic field at centre of infinite solenoid carrying current *I*.

Ans.  $N \rightarrow \text{total no. of lines}$ 

 $L \rightarrow total length$ 

$$n \rightarrow \frac{N}{L} = \frac{no.of \ turns}{length}$$

Proof:

<u>Step 1</u>.

Make ampere circuit loop

Apply ampere circuit law for loop ABCD

 $\oint$  H. dl = N.I

## ABCDA

<u>Step 2</u>.

Ampere circuit loop sub parts

$$\begin{split} \int_{AB} H. \, dl + \int_{BC} H. \, dl + \int_{CD} H. \, dl + \int_{DA} H. \, dl = N. I. \\ \int_{AB} H. \, dl + 0 + \int_{CD} H. \, dl + 0 = N. I. \\ 2\int H. \, dl &= NI \\ 2H\int dl &= NI \\ 2HL &= NI \\ H &= \frac{N.I}{2.L} \\ H_{total} &= 2. \left(\frac{N.I}{2.L}\right) = \left(\frac{N}{L}\right). I \end{split}$$



$$H_{total} = nI$$

B =  $\mu_0 H_{total}$  (for air) B =  $\mu_0 nI$  (for air solenoid) B =  $\mu_0 . \mu_r . nI$ V Relative permeability material







- Q.10. Use ampere circuit law to find magnetic field in and around a toroid?
- Ans. <u>Case I</u>.
- Inside Toroid (iron part)



Ampere Circuit Law  $\oint$  H. dl = NI H.∮dl = NI H ( $2\pi r$ ) = NI $=\left(\frac{N}{2\pi r}\right)$ . I Н = *nI* Н В = μΗ В  $= \mu n I$ Case-II. (Loop 2) Outside Toroid  $\oint$  H. dl = N (+I) + N(-I) H.∮dl =0 H.2πr = 0 Н = 0 В = 0 Case-III. (Loop 3)  $\oint$  H. dl = 0 H.2πr = 0 = 0 Н В = 0